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continuous and discrete signals are defined as E∞ = Z∞ −∞ |x(t)|2dx and E ∞ = X∞ n=−∞ |x[n]|2, and P∞ = lim T→∞ 1 2T Z T −T |x(t)|2dx and P ∞ = lim N→∞ 1 2N +1 XN n=−N |x[n]|2. Using these we can compute each part of the given problem. Part (a): For this signal we find E∞ = Z∞ 0 e−4tdt = e−4t −4 ∞ 0 = 1 4, and P∞ = lim T→∞ 1 2T Z T 0 e−4tdt = lim T→∞

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signals and systems 4. The continuous-time system consists of two integrators and two scalar multipliers. Write a differential equation that relates the output y(t) and the input x(t). ( ) ( ) ( ) ( ) a 1 w t a 2 y t x t dt dw t e t ----- (1) Since w(t) is the input to the second integrator, we have dt dy t w t ( ) ( ))----- (2)

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